

NTL105 CONNECTION AND SETTING UP

Getting Started Guide





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1 CONNECTION TO PC

NTL Browser is a software tool designed to communicate with NTL105 through **NTL Adp Board** (or other interface adapter designed by NTLab company). It is provided as a zip file. It is available on NTLab company FTP server. Link (password and login) may be provided on request.

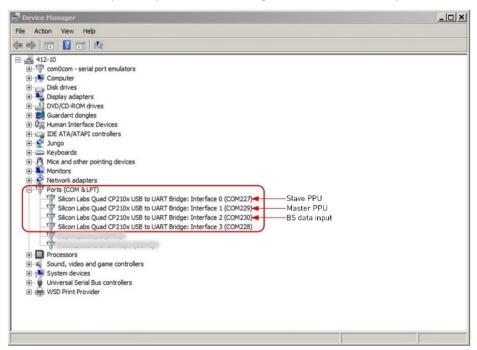
Follow to the next steps to connect NTL 105:

- 1. Install NTL Browser on computer.
- 2. Install CP210x drivers on computer. Utility software downloadable from:
 https://www.silabs.com/products/development-tools/software/usb-to-uart-bridge-vcp-drivers
- 3. Connect NTL105 to the NTL Adp Board.
- 4. Connect Master and Slave antennas to NTL105 (connector X1 and X2 of the NTL105, respectively).
- 5. Connect NTL Adp Board to PC through mini USB cable (connector X1 of the NTL Adp Board).

NTL Adp Board provides +5V supply voltage for navigation module and simplifies connection to host computer.

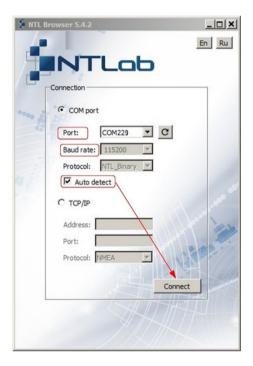
NTL105 UART outputs is available on PC via on-board 4xUART to USB converter (CP210x based) as virtual COM ports.

At this stage, four virtual COM ports should be detected on operating system. Three of four virtual COM ports provide access to the NTL105. The Master PPU is available through COM229 (Interface 1), the Slave PPU – through COM227 (Interface 0) and Base Station (BS) data input – through COM230 (Interface 2). See example below. The slave PPU doesn't require any additional setting, so the further description will be skipped.





- 6. Run NTL Browser on computer. Then configure it:
 - Select interface language in the upper right corner of welcome page;
 - Connect to the COM229 Port. Port number could be different for alternative PC;
 - Set up 115200 Baud rate and NTL Binary Protocol type or Set up Auto detect checkbox to define them automatically
 - Click on the Connect button to continue.

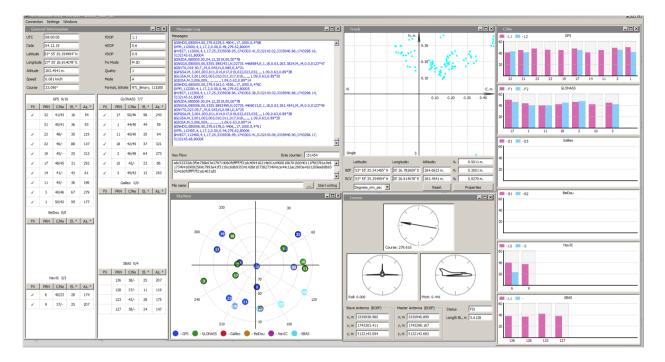


NTL Browser Main page consists of the multiple windows, that can be switched on/off in **Windows** toolbar. Select necessary windows for your work.





Windows display different navigational information and may be configured on demand (see example below).



Message Log window displays periodical messages coming from the receiver. While the interface mode is NTL Binary, messages have binary format. You can see textual interpretation of their content in Message Log window printed in blue color. If the interface mode is NMEA, received data is printed directly in Message Log in black color.

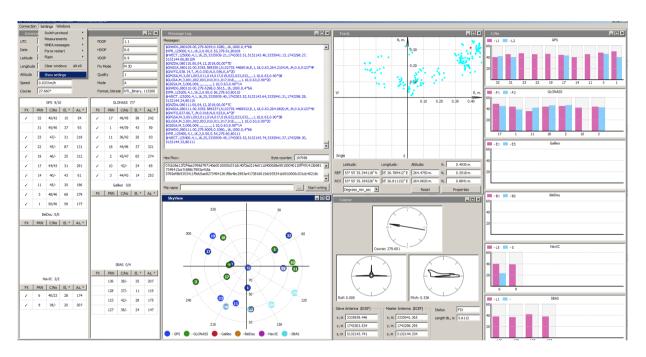


2 HEADING DETERMINATION MODE (SINGLE+HEADING)

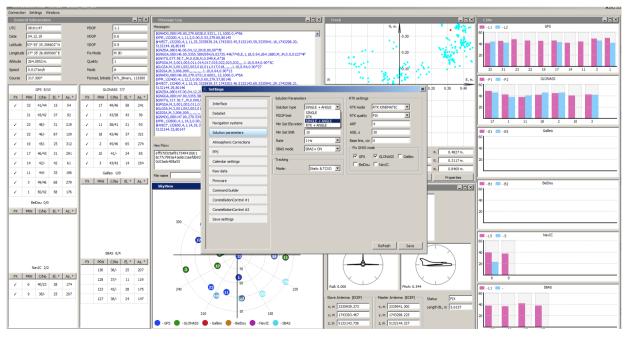
By default, master PPU channel operates in *Single solution* mode and processes GPS and GLONASS signals. While operating in NTL Binary mode, configuration settings are available in **Settings** menu.

Heading determination mode can be switched on:

1. Select the Settings/Show settings section

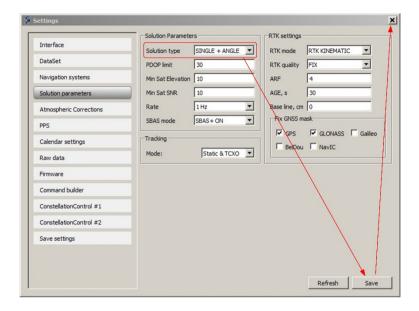


2. Then select the Solution parameters section



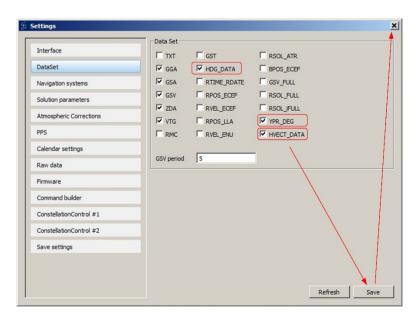


- In the Solution Parameters sub-section, select 'SINGLE+ANGLE' as the Solution type;
- Click on the **Save** button. Exit the **Settings** section.



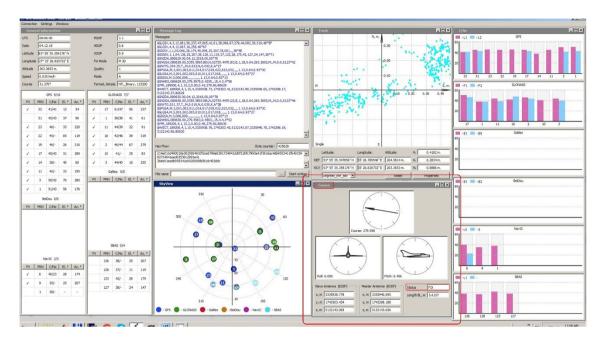
The information about 2D orientation (Heading) is displayed in the **Course** window, which represents information from HDG_DATA (it is available in NMEA mode to), YPR_DEG, HVECT_DATA messages.

- 3. Ensure that appropriate messages are switched on. To do this:
 - Select the Settings/Show settings/DataSet section;
 - Click on the Save button. Exit the Settings section.





4. Wait for the FIX Status in Course window (maximum accuracy mode):



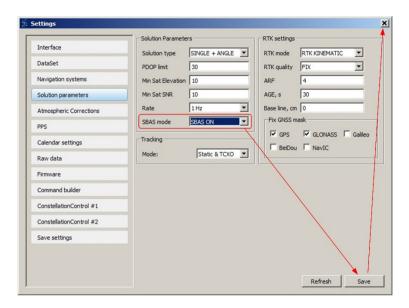
Positioning mode is standalone (Single). Orientation estimates are based on determination of mutual position of Master and Slave antennas (moving-base RTK mode).



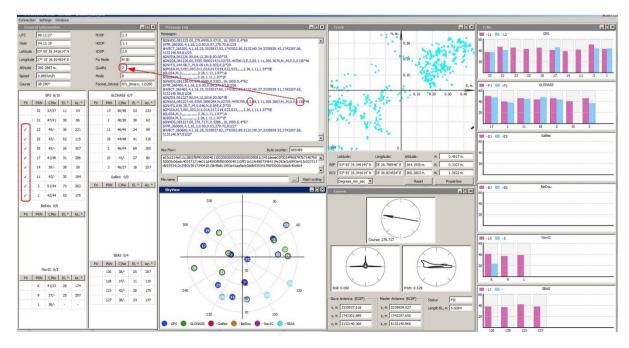
3 DGPS MODE

DGPS mode can be switched on:

- 1. Switch on SBAS ON mode:
 - Select the Settings/Show settings/Solution Parameters section. In the Solution Parameters sub-section select 'SBAS ON' as the SBAS mode;
 - Click on the Save button. Exit the Settings section.



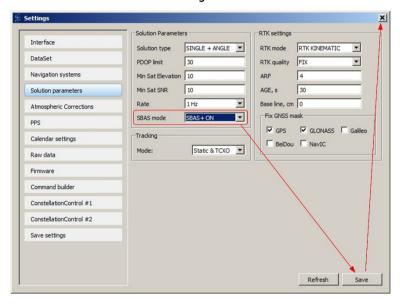
While we are in DGPS mode, only GPS+SBAS satellites will be used. DGPS mode indicated with '2' in the General Information window in the Quality sub-section (or status field of GGA message). See below.





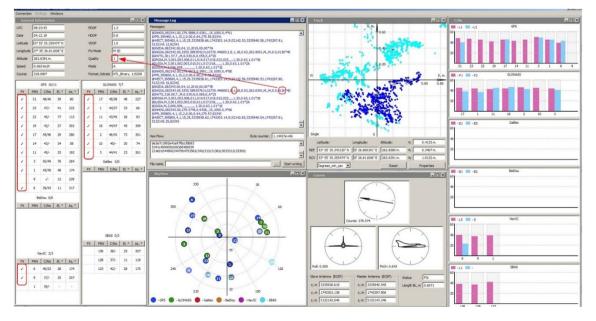
2. Switch on SBAS+ mode:

- Select the Settings/Show settings/Solution Parameters section. In the Solution Parameters sub-section select 'SBAS + ON' as the SBAS mode:
- Click on the Save button. Exit the Settings section.



In this mode all available GNSS satellites will be used in navigation solution. GPS satellites will get full set of SBAS corrections. Measurements based on other GNSS systems will get only consistent part of SBAS corrections.

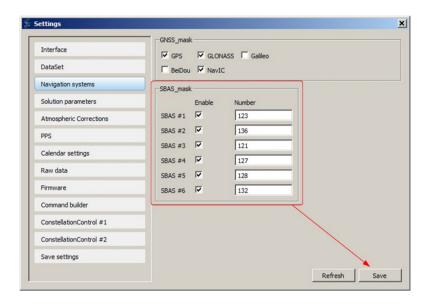
While we are in SBAS+ mode SBAS satellite number is indicated in the last field of GGA message. GGA status field will remain '1' (displayed in the General Information window in the Quality sub-section). See below.



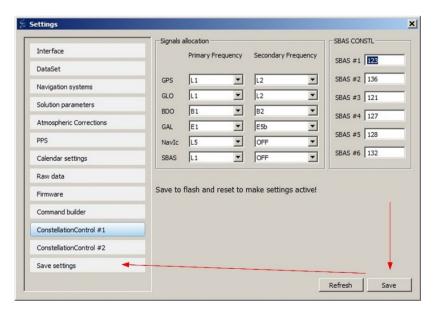


Internal logic of NTL105 selects the best SBAS satellite to be used in navigation solution. Up to 6 SBAS satellites may be tracked simultaneously.

- Select the Settings/Show settings/Navigation systems section to control SBAS satellites manually. By default, NTL105 module tracks EGNOS and GAGAN satellites;
- Click on the Save button.



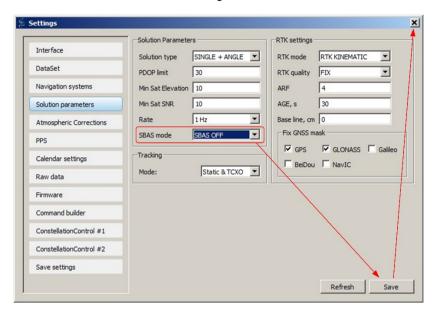
• Select the ConstellationControl#1 section to change SBAS subsystems to be used



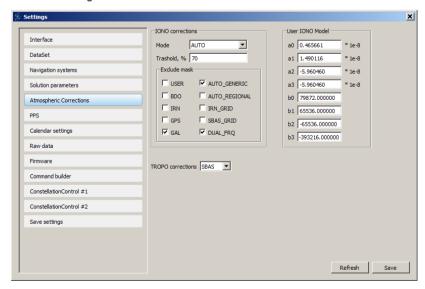
SBAS satellite numbers 120...158 may be programmed on this page. Settings would have become active only after they are saved into FLASH memory and receiver reloaded.



- 3. Switch off SBAS mode (SBAS OFF) to enter regular SINGLE positioning mode:
 - Select the Solution Parameters section. In the Solution Parameters sub-section select
 'SBAS OFF' as the SBAS mode:
 - Click on the Save button. Exit the Settings section.



While you are in SINGLE positioning mode, tropospheric and ionospheric corrections are performed in accordance with GNSS ICDs. Due to multi constellation support there is a variety of available correction modes. Parameters in section Settings/Show settings/Atmospheric Corrections allow control over correction methods. Recommended parameters are on the picture below. Refer to «GNSS-PPU-SETUP-GUIDE-6-62-00.pdf» for details before making modifications.



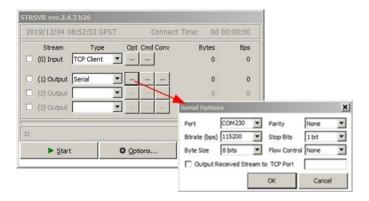


4 DIFFERENTIAL POSITIONING MODE (RTK+HEADING)

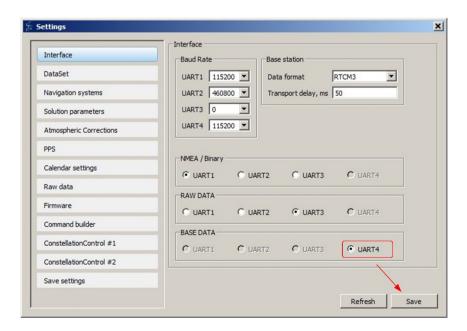
We should provide base station measurements data to make RTK positioning mode available. In this example we will receive base station data from local VRS network via Internet. STRTOSVR utility will be used to redirect data flow to COM230 (Interface2).

Differential positioning mode can be switched on:

1. Run strsvr.exe¹ utility from RTK LIB package



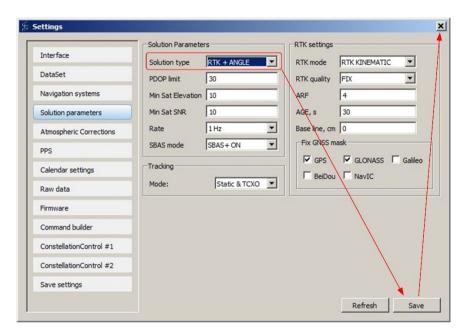
- 2. VRS network provides data in RTCM3 format. Novatel 0EMv7 data format may be used as an alternative. Appropriate settings should be made in receiver:
 - Select the Settings/Show settings/Interface section. Make sure UART4 is set up



 $^{^{1}}$ Required tools are available on NTLab FTP server. Link (password and login) may be provided on request.

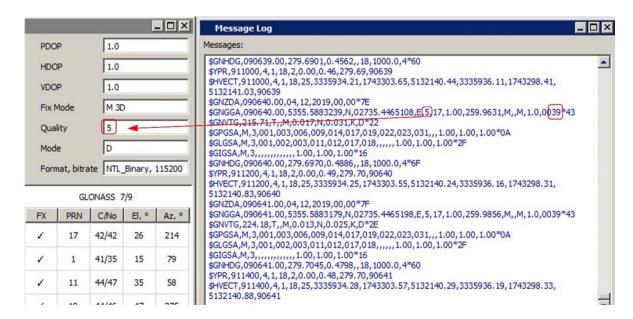


- Click on the Save button.
- Select the **DataSet** section. Make sure, the necessary messages are selected.
- Select the Settings/Show settings/Solution parameters section. In the Solution type subsection, select 'RTK+ANGLE';
- Click on the Save button. Exit the Settings section.



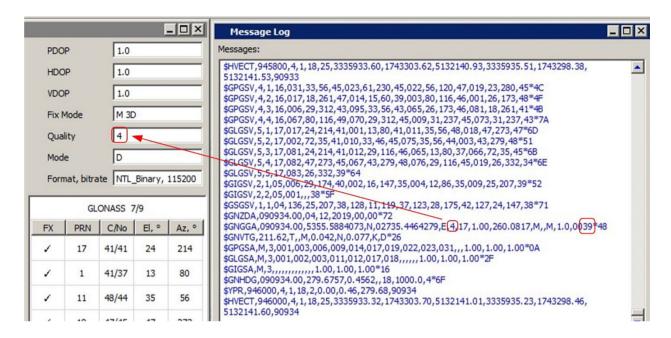
RTK settings sub-section contains some control parameters defining RTK positioning mode. Refer to «GNSS-PPU-SETUP-GUIDE-6-62-00.pdf» for details.

At first, receiver enters RTK FLOAT mode (Quality '5'):





In some time, receiver enters RTK FIX mode (Quality '4') - the most accurate positioning mode. Base station number, corrections age and solution status are indicated in GGA messages.



Another one NTL10X-series receiver may be used as a reference receiver instead of VRS network. Refer to Section 5 to setup receiver as a source of raw ranging data.

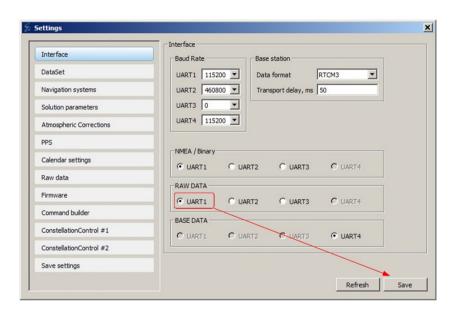


5 GENERATION OF RAW RANGING DATA

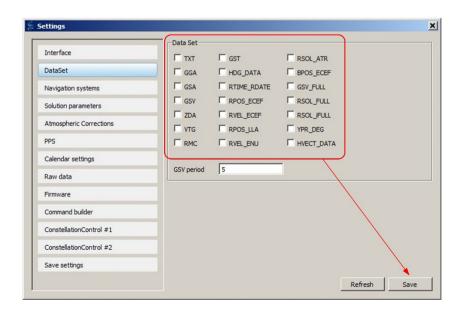
Navigation module can be used as a source of raw ranging data for further post processing or differential positioning.

This can be done as follows:

Select the Settings/Show settings/Interface section. In the RAW DATA sub-section set UART1. Click
on the Save button.

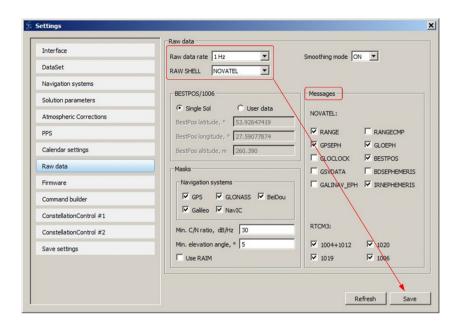


 Select the DataSet section. In the Data Set sub-section deselect all checkboxes. Click on the Save button. After this action module stops NTL Binary periodic messages generation

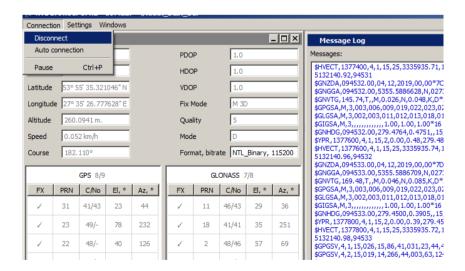




3. Select the Raw data section. In the Raw data rate sub-section, select '1 Hz' and 'NOVATEL' as the RAW SHELL. In the Messages sub-section can be specified NOVATEL and RTCM3 messages type. Click on the Save button. Refer to «GNSS-PPU-SETUP-GUIDE-6-62-00.pdf» for other details.



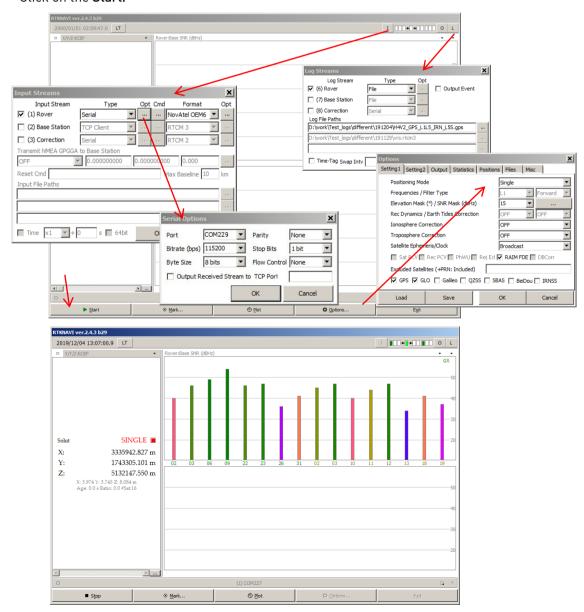
- 4. Exit the **Settings** section.
- 5. Exit NTL Browser to release COM port. To do this, select Connection/Disconnect



Generation of raw data in Novatel format is shown on the picture below. RTCM3 is not suitable to transmit measurements made on NavIC signals. RTKNAVI tool may be used to visualize and write Raw data measurements.



- 6. Run the rtk_navi.exe2 utility:
 - Click on the 'I' button;
 - In the Format sub-section select 'NovAtel OEM6':
 - In the Opt sub-section (Serial Options window) select 'COM229' as the Port, and '115200' as the Bitrate. Click on the 'OK' button;
 - Click on the 'L' button. Specify Log File Paths, to write raw data into. Click on the 'OK' button;
 - Click on the 'Options' button. Set Positioning Mode to 'Single'. Click on the 'OK' button;
 - Click on the Start.

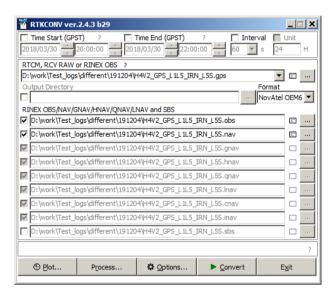


² Required tools are available on NTLab FTP server. Link (password and login) may be provided on request.

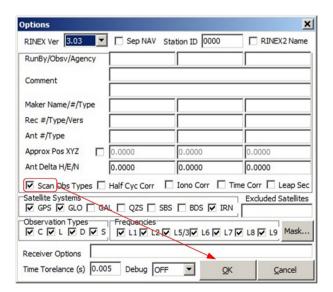


The **rtk_navi.exe** utility get receiver position, so raw data accepted and processed. But RTKNAVI can't visualize NavIC data.

- 7. Convert Novatel Raw data we have already written down into RINEX format to check ability of NavIC measurements:
 - Run the rtkconv.exe3 utility



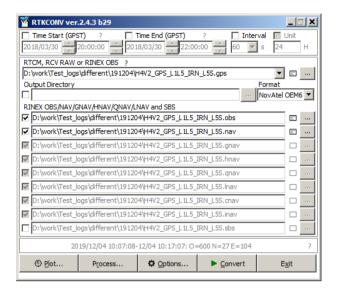
- Select source file and data format;
- Setup **Options** as on the picture below. Click on the '**OK**' button.



 $^{^3}$ Required tools are available on NTLab FTP server. Link (password and login) may be provided on request.



• Click on the 'Convert' button



NavIC measurements present in resulting *.obs file:

> 2019 12 4 10 7 8.0000000 0 20							
16 38522313.570 151169828.197	69.335	40.000					
G 2 24630716.765 129435262.895	2572.844	41.000					
G26 23624243.771 124146245.069	1501.286	33.000	23624249.857	96737376.134	1169.861	39.000	
R11 22403606.853 119718101.054	-2960.565	44.000	22403606.908	93114053.369	-2302.530	43.000	
1 2 39306608.520 154247570.868	831.031	37.000					
R18 22083165.970 117881445.428	-3605.341	42.000	22083170.497	91685575.641	-2804.068	46.000	
R 2 20318455.936 108423181.073	-2319.539	45.000	20318460.177	84329159.829	-1804.028	45.000	
R10 22988150.773 122626067.580	-3475.146	41.000					
G31 24257878.030 127476010.358	-3418.558	40.000	24257881.611	99331969.997	-2663.750	38.000	
G23 20569294.053 108092363.974	224.816	46.000					
G22 23057366.475 121167269.238	-3020.985	46.000					
13 40314726.643 158203644.885	-42.358	35.000					
R13 22150554.420 118282615.452	4169.452	35.000	22150557.883	91997639.769	3242.372	31.000	
I 4 39960693.172 156814361.183	376.540	35.000					
G 3 21217036.341 111496272.946	-2265.922	46.000	21217041.075	86880231.915	-1765.889	43.000	
R 3 19548086.940 104642446.091	1218.198	47.000	19548087.689	81388555.405	947.588	45.000	
G 6 21828941.127 114711862.118	699.199	49.000	21828946.292	89385866.070	544.793	49.000	
R12 20439991.801 109186791.705	656.740	48.000	20439992.686	84923050.965	510.642	45.000	
G 9 21018769.902 110454384.309	1973.633	54.000	21018773.753	86068408.483	1537.971	48.000	
R19 21203156.737 113422577.826	-186.546	37.000	21203158.576	88217576.426	-145.262	39.000	

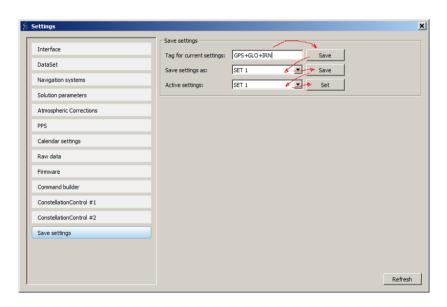


6 NON-VOLATILE FLASH

All receiver settings made in NTL Browser will be lost after the next power off if they are not saved into nonvolatile memory. NTL105 receiver allows two sets of controls to be saved into FLASH.

To do this:

- 1. Select Settings/Show settings/Save Settings section;
- 2. Enter textual tag for current scope of control parameters (optionally);
- 3. Select a name for current scope of controls: SET1 or SET2;
- 4. Select a set of controls to be loaded with (active set): DEFAULT or SET1 or SET2.



During the next power on saved setting will be restored and used during receiver start up.



CONTACT

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